

Symposium Program			
Stockholm Time (GMT+2)		Sweden Hall - 07 June 2023 https://kth-se.zoom.us/j/64817437048	
Symposium Moderator:		Ali Haydar Ercan, Symposium Moderator	
DAY ONE	10:45 - 11:00	Opening Session Ricardo Vinuesa, ISUDEF'23 Symposium Chair, KTH Royal Institute of Technology, Sweden Adil Gasimov, ISUDEF'24 Symposium Chair, National Aviation Academy, Azerbaijan	
	11:00 - 11:30	Introductory Keynote Session Max Platzer, Lifetime Honorary President of SARES T. Hikmet Karakoç, Founding Chair of SARES Symposiums	
	11:30 - 13:00	Keynote Speaker Session I	Session Chair: Hikmet Karakoç <i>Direct numerical simulation of a thermal turbulent boundary layer: an analogy to simulate bushfires and a testing bed for artificial intelligence remote sensing of bushfire propagation.</i>
			Julio Soria, Monash University, Melbourne, Australia <i>Student UAV projects at KTH</i>
			Raffaello Mariani, KTH Royal Institute of Technology, Sweden <i>Unmanned Aerial Vehicles Cooperation for the monitoring of Greenhouse Gases</i>
			Glauco Caurin, University of São Paulo, Brasil
	13:00-14:00 Lunch Break		
	14:00 - 15:15	Industrial Special Session I	Session Chair: Ricardo Vinuesa <i>Hydrogen powered UAVs</i> Hüseyin Devrim, TEKSIS İleri Teknolojiler, Türkiye <i>Air Mobility Initiative U-Space (AMIUS) - Together for secure UAM operations in U-space</i> Mona Moren, Airbus Urban Mobility (AUM), Germany <i>Design Considerations for Tethered Unmanned Air Systems</i> Ahmet Nezir Ertürk, Otonom Teknoloji, Türkiye
	15:15 - 15:45	1st Technical Session	Session Chair: Gerardo Zampino <i>Propulsion and Fuel Systems Design of a Target UAV with High Subsonic Speed.</i> Ali Avanlier, Serhat Yılmaz <i>Parametric Approach to Initial Weight Determination at Preliminary Design of a Quadrotor Cargo UAV.</i> Fikret Kamil Corbaci, Yunus Emre Dogan

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DAY TWO	10:30 - 11:30	Session Chair: Ali Haydar Ercan <i>Marine Autonomy: Research and Applications</i> Sanjay Sharma, University of Plymouth, England, UK <i>UAV noise: integrating biodiversity assessment into sustainable aviation</i> Mike Wood, University of Salford, UK			
	11:30 - 12:45	Industrial Special Session II	Session Chair: Raffaello Mariani <i>Modern GIS Trends</i> Barış Uz, ESRI Türkiye, Türkiye <i>Preliminary design of a solar-powered UAV</i> Alessandro Borgia, Team Icarus PoliTO, Italy <i>GNSS Architectures for high dynamics navigation</i> Miguel Ángel Gómez López, National Institute of Aerospace Technology (INTA), Spain		
			12:45-13:00 Break		
			13:00 - 13:30	2nd Technical Session	Session Chair: Soledad Le Clainche Martínez <i>Comparative Analysis of AI-Supported Drone Operations: Evaluating Critical Aspects among Pilot Groups</i> Omar Alharasees, Utku Kale <i>Mathematical Modeling of Staging Analysis for Launch Vehicles and Design of Collision Prevention Algorithm</i> Bahadır Erdenk
			13:30 - 15:00	Keynote Speaker Session III	Session Chair: Raffaello Mariani <i>Reduced order models and machine learning in aerospace engineering</i> Soledad Le Clainche Martínez, Universidad Politécnica de Madrid (UPM), School of Aeronautics, Spain <i>Nontraditional Attitude Filtering with Uncertain Process Noise</i> Chingiz Hajiyev, Istanbul Technical University, Türkiye <i>The working bees to combat climate change</i> Olga Lucia Quintero Montoya, Universidad EAFIT, Colombia

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T H R E E	10:00 - 12:00	Keynote Speaker Session IV	Session Chair: Gerardo Zampino
			<i>Urban flow predictions: understanding uncertainties to widen their application</i> Clara García-Sánchez , Delft University of Technology, The Netherlands
			<i>Energetic Attribute of Fuel Cells in Hydrogen Aviation Including UAVs</i> Birol Kilkış , OSTIM Technical University, Türkiye
			<i>Exploring the Future of Unmanned Aircraft Applications and Flight Safety</i> Rikard Tyllström , Lund university School of Aviation, Sweden
D A Y	12:00 - 13:15	Industrial Special Session III	Session Chair: Birol Kilkış
			<i>Fast-time Large-scale Simulations for Airspace Capacity Assessment</i> Milan Rollo , AgentFly Technologies, Czechia
			<i>Revolutionizing Logistics for a Sustainable Future: Aerit's Journey to Create Global Drone Delivery Networks</i> Alexander Perrien , Aerit, Sweden
			<i>The Sustainable Urban Mobility Indicators (SUMI) Framework</i> Anna Palaiologk , Future Needs Management Consulting Ltd., Greece
13:15 - 13:45 Closing Remarks			

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